[This question paper contains 6 printed pages.]

## Your Roll No.....

J

Sr. No. of Question Paper: 7880

: 32347504

Name of the Paper

Unique Paper Code

Microprocessors

Name of the Course

B.Sc. (H) Computer Science:

DSE-1

Semester

V

Duration: 3 Hours

Maximum Marks: 75

## Instructions for Candidates

- 1. Write your Roll No. on the top immediately on receipt of this question paper.
- 2. Attempt all questions from Section A.
- 3. Attempt any four questions from Section B.
- 4. Attempt all parts of a question together.

## SECTION A

1. (a) "Segment and Offset Addressing Scheme Allows Relocation" Justify the statement. (2)

P.T.O.

- (b) Differentiate between MOVZX and MOVSX instruction with the help of an example. (3)
- (c) Explain how the Near and Far CALL instructions function. (3)
- (d) What is a displacement? How does it determine the memory address in a MOV [2000H], AL instruction?
- (e) Which three minimum mode 8086/8088 pins are decoded to discover whether the processor is halted?

  (3)
- (f) Contrast a memory mapped 1/0 system with an isolated 1/0 memory (3)
- (g) List the number of data items stored in each of the following memory devices and the number of bits in each datum:
  - (i)  $16K \times 1$
  - (ii)  $2K \times 4$
  - (iii)  $64K \times 4$  (3)

- (h) What is the purpose of D, S and NT bits of FLAG register? (3)
- (i) Which type of JMP instruction (short, near, or far) assembles for the following:
  - (i) If the distance is 0210H bytes
  - (ii) If the distance is 0020H bytes
  - (iii) If the distance is 10000H bytes (3)
- (j) What three modes of operation are available to 8255 programmable peripheral interface? (3)
- (k) Which conditional jump instructions follow the comparison of signed and unsigned numbers?
- (l) What is the purpose of ICW1, ICW2 and OCW1 in programming the 8259A programmable interrupt controller? (3)

## SECTION B

(a) What do you mean by the program-invisible registers? Explain the purpose of IDTR and TR.
 (5)

P.T.O.

(b) What is an assembly language directive? Explain 5 the purpose of following directives:

- (i) .BREAK
- (ii) .386
- (iii) .STARTUP
- (iv) EQU

(5)

- 3. Explain the difference between:
  - (a) LDS and LSS
  - (b) PUSHF and PUSHFD
  - (c) IRET and IRETD
  - (d) INSW Md OUTSB
  - (e) JAE and JGE

(10)

- 4. (a) Draw and explain the write bus cycle for 8086/8088 microprocessor. (5)
  - (b) Give the new features made available in Pentium microprocessor. (5)

- (a) Explain how the command register programs the 5. operation of the 8237 DMA. (5)
  - (b) Describe the register relative addressing mode of the 8086 with the help of an example. (5)
- Write the function of following instructions: 5.
  - (a) NOP
  - (b) BOUND
  - (c) CMOV
  - (d) POPAD

- (e) STOSW (10)

  (a) Given that DS = 1100H, BX=0200H, LIST=0250H and SI=0500H. Determine the address accessed by each of the following instructions, assuming real mode operation:
  - (i) MOV LIST[SI], EDX
  - (ii) MOV CL, LIST[BX+SI]
  - (5)(iii) MOV CH, [BX+SI]

P.T.O.

(b) How do CALL and RET instructions affect stack? Explain with an example.